# AdS/CFT duality for non-anticommutative supersymmetric gauge theory 

Chong-Sun Chu, Shou-Huang Dai and Douglas J. Smith<br>Centre for Particle Theory and Department of Mathematics, Durham University, Durham, DH1 3LE, U.K.<br>E-mail: chong-sun.chu@durham.ac.uk, shou-huang.dai@durham.ac.uk,<br>douglas.smith@durham.ac.uk

Abstract: We construct type IIB supergravity duals of non-anticommutative deformed $\mathcal{N}=4 \operatorname{SU}(N)$ gauge theories. We consider in particular deformations preserving $\mathcal{N}=(1,0)$ and $\mathcal{N}=(1 / 2,0)$ supersymmetry. Such theories can be realised on $N$ D3-branes in specific self-dual 5 -form backgrounds. We show that the required 5 -form field strengths can be produced by configurations of intersecting D3-branes and we are then able to construct the supergravity solutions in the near-horizon limit. We consider some consequences of this duality, in particular showing that the gravity duals predict that the dimensions of a subset of BPS operators are not modified by the deformation.

Keywords: AdS-CFT Correspondence, Superspaces, Intersecting branes models,
Supersymmetric gauge theory.

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## 1. Introduction

The AdS/CFT correspondence [1] is an explicit realization of the holographic principle [5, [5]. It is the best understood example of a gauge/gravity duality and offers promising opportunities to tackle and understand some of the most difficult problems in theoretical high energy physics such as the quantum properties of spacetime and the confinement problem in gauge theory.

Owing to different motivations, various generalizations of the dualities have been considered. We note in particular the ones [7, 8] for noncommutative supersymmetric YangMills and [9] where the duality is characterized by a very interesting extended action of $\mathrm{SL}(2, \mathbb{Z})$ [11, 10]. Both of these deformations of the original AdS/CFT duality are motivated by having a deformed $*$-product on the field theory side. In the first case, the spacetime is deformed by a Moyal product induced by a constant NSNS B-field which lives on the worldvolume of the D3-branes, while in the second case, the product between fields carrying different $\mathrm{U}(1)$ charges is deformed due to a nontrivial twist in the TsT-transformation. In this regard, it is natural and of interest to construct a gauge/gravity duality for the
non-anticommutative supersymmetric gauge theory [12, 13] where the fermionic coordinates of the superspace are deformed with a non-anticommutative $*$-product. ${ }^{1}$ The goal of this paper is to construct the gauge/gravity duality for the non-anticommutative deformed $\mathcal{N}=4$ supersymmetric Yang-Mills theory.

Non-anticommutative supersymmetric theories preserve a chiral fraction of the supersymmetries. That this is possible is because these theories are defined in Euclidean space and the left and right chiral sectors are not related by a complex conjugation. Due to their different supersymmetric structure, a priori these theories could have quite different quantum properties from their undeformed cousins. Although power counting nonrenormalizable, nevertheless they are renormalizable [15, 16] basically because in a Feynman diagram computation, the Hermitian conjugate partners which would be needed to generate divergent counter terms are missing. Moreover due to the existence of a superspace formulation, non-renormalization theorems exist as usual. In addition to having a very interesting mechanism of supersymmetry breaking, non-anticommutative supersymmetric theories also possess interesting non-perturbative properties [17].

In the original Maldacena AdS/CFT correspondence, the amount of preserved supersymmetry is maximal. Since holography is believed to be a generic property of quantum gravity, it is interesting to understand how gauge/gravity duality works in a less or nonsupersymmetric setting, especially when the supersymmetry is preserved in a non-standard manner. This is another motivation for our goal.

Non-anticommutativity in string theory [18-20] was first discovered by Ooguri and Vafa [18], who observed that a self-dual graviphoton field strength $C_{\mu \nu}$ induces a deformation in the fermionic part of the 4-dimensional superspace. Seiberg proposed another type of deformation which imposes commutativity in the chiral coordinates [12]. The deformation keeps $\mathcal{N}=1 / 2$ supersymmetry in the case of simple supersymmetry, or more specifically, $\mathcal{N}=(1 / 2,0)$ of the original $\mathcal{N}=(1 / 2,1 / 2)$ supersymmetry ${ }^{2}$. The deformed superspace has algebra

$$
\begin{align*}
\left\{\theta^{\alpha}, \theta^{\beta}\right\} & =C^{\alpha \beta},  \tag{1.1}\\
\left\{\bar{\theta}^{\dot{\alpha}}, \bar{\theta}^{\dot{\beta}}\right\} & =\left\{\theta^{\alpha}, \bar{\theta}^{\dot{\beta}}\right\}=0,  \tag{1.2}\\
{\left[y^{\mu}, y^{\nu}\right] } & =\left[y^{\mu}, \theta^{\alpha}\right]=\left[y^{\mu}, \bar{\theta}^{\dot{\alpha}}\right]=0, \tag{1.3}
\end{align*}
$$

where $y^{\mu}=x^{\mu}+i \theta^{\alpha} \sigma_{\alpha \dot{\alpha}}^{\mu} \bar{\theta}^{\dot{\alpha}}$. The deformation is described by the constant $C^{\alpha \beta}=$ $C_{\mu \nu}\left(\sigma^{\mu \nu}\right)^{\alpha \beta}$.

The generalization to the extended supersymmetry is immediate. For the $\mathcal{N}=2=$ $(1,1)$ case, the deformation generalizes to

$$
\begin{equation*}
\left\{\theta^{\alpha i}, \theta^{\beta j}\right\}=C^{\alpha \beta i j}, \quad i=1,2, \tag{1.4}
\end{equation*}
$$

[^0]with all the other (anti)commutative relations remaining undeformed. The deformation parameter $C^{\alpha \beta i j}$ obviously satisfies $C^{\alpha \beta i j}=C^{\beta \alpha j i}$. The deformation parameter can be decomposed into irreducible parts 21, 22]
\[

$$
\begin{equation*}
C^{\alpha \beta i j}=\epsilon^{\alpha \beta} \epsilon^{i j} I+C^{(\alpha \beta)(i j)} \tag{1.5}
\end{equation*}
$$

\]

The deformation described by the first term is called the singlet deformation. It preserves Euclidean $\mathrm{SO}(4)$ invariance and $\mathrm{SU}(2) R$-symmetry, and breaks $\mathcal{N}=(1,1)$ supersymmetry down to $\mathcal{N}=(1,0)$. The singlet deformation can be obtained from string theory in a constant RR scalar background [23]. The deformation described by the second term in (1.5) is called the non-singlet deformation. It retains $\mathcal{N}=(1,0)$ supersymmetry for generic $C^{\alpha \beta i j}$. However for particular deformation parameters such that

$$
\begin{equation*}
C^{\alpha \beta i j}=C^{\alpha \beta} b^{i j} \tag{1.6}
\end{equation*}
$$

and with $\operatorname{det} b=0$, the preserved supersymmetry is enhanced to $\mathcal{N}=(1,1 / 2)$ 21. The non-singlet deformation can be obtained from string theory in a constant RR 5form background $23-25$. $\mathcal{N}=4$ lightcone superspace could be defined. However nonanticommutative deformations of it have not been considered.

The non-anticommutative deformation (1.6) can be obtained from string theory in a particular RR 5-form background of the form 24, 25]

$$
\begin{equation*}
F_{\mu \nu a b c}=f_{\mu \nu} g_{a b c} \tag{1.7}
\end{equation*}
$$

where $\mu, \nu=0,1,2,3$ denote the 4 -dimensional indices and $a, b, c,=4, \ldots, 9$ are the indices of the transverse space. This 5 -form is self-dual both in the 4 -spacetime directions and in the transverse 6 dimensions

$$
\begin{equation*}
f_{\mu \nu}=\frac{1}{2!} \epsilon_{\mu \nu \rho \sigma} f_{\rho \sigma}, \quad g_{a b c}=\frac{-i}{3!} \epsilon_{a b c d e f} g_{d e f} \tag{1.8}
\end{equation*}
$$

In other words, the RR 5-form has the non-vanishing components $F_{\mu \nu a b c}$ and satisfies the "double self-duality" condition

$$
\begin{align*}
F_{\mu \nu a b c} & =\frac{1}{2!} \epsilon_{\mu \nu \rho \lambda} F_{\rho \lambda a b c} \\
F_{\mu \nu a b c} & =\frac{-i}{3!} \epsilon_{a b c d e f} F_{\mu \nu d e f} \tag{1.9}
\end{align*}
$$

Note that $g_{a b c}$ and hence the RR 5-form is necessarily complex since we are dealing with Euclidean signature.

The action for the non-anticommutative SYM theory can be obtained using the superspace construction. For the deformed $\mathcal{N}=(1 / 2,1 / 2)$ superspace, see [12] for pure SYM and [26] for SYM theory with matter. For the deformed $\mathcal{N}=(1,1)$ case, one may use harmonic superspace. See 27, 28, 23, 29] for the case with singlet deformation, and 27, 30-32] for the non-singlet deformation. It can also be obtained from string theory as the worldvolume action of D3-branes. More specifically, the pure SYM action with $\mathcal{N}=(1 / 2,0)$ or $\mathcal{N}=(1,0)$ supersymmetry can be obtained as the worldvolume action of D3-branes in a
orbifold with constant graviphoton background [33, 24]. Deformations of the $\mathcal{N}=4$ SYM action with $\mathcal{N}=(1 / 2,0)$ or $\mathcal{N}=(1,0)$ supersymmetry can be obtained as the worldvolume action of D3-branes in a specific configuration of RR 5 -form flux [25]. In this paper we will be interested in constructing a gauge/gravity duality for the non-anticommutative deformed $\mathcal{N}=4$ SYM theories with $\mathcal{N}=(1 / 2,0)$ and $\mathcal{N}=(1,0)$ supersymmetry.

The paper is organized as follows. In section 2 , we present the construction of the non-anticommutative deformed $\mathcal{N}=4$ SYM theories with $\mathcal{N}=(1 / 2,0)$ and $\mathcal{N}=(1,0)$ supersymmetry as the worldvolume action of D3-branes with a particular configuration of RR 5-form flux. In section 3, we realize the configurations as intersecting brane systems and obtain the supergravity duals of these non-anticommutative deformed $\mathcal{N}=4$ gauge theories. In section 4 , we focus on the theory with $\mathcal{N}=(1,0)$ supersymmetry and analyse the duality. In particular we perform a standard bulk-to-boundary analysis to extract the two point correlation function for the field theory. We find that the deformation modifies only the overall coefficient, but leaves the form of the two-point function unchanged. This implies that there exists a sector of BPS operators whose dimensions are unmodified by the deformation.

## 2. The non-anticommutative deformations of the $\mathcal{N}=4 \mathrm{SYM}$

### 2.1 D3-brane realization of $\mathcal{N}=4$ SYM

Consider $N$ D3-branes in the 0123-directions. The Lorentz group $\mathrm{SO}(10)$ is decomposed into $\mathrm{SO}(4) \times \mathrm{SO}(6)$ and the spin fields can be decomposed as $\left(S^{\alpha} S^{A}, S_{\dot{\alpha}} S_{A}\right)$ and $\left(\tilde{S}^{\beta} \tilde{S}^{B}, \tilde{S}_{\dot{\beta}} \tilde{S}_{B}\right)$ where $S^{\alpha}, \tilde{S}^{\alpha}$ and $S_{\dot{\alpha}}, \tilde{S}_{\dot{\alpha}}(\alpha, \dot{\alpha}=1,2)$ are four dimensional Weyl spinors and $S_{A}, \tilde{S}_{A}$ and $S^{A}, \tilde{S}^{A}(A=1,2,3,4)$ are six-dimensional Weyl spinors. The presence of a constant RR background can be described using the RR vertex operator. In the ( $-\frac{1}{2},-\frac{1}{2}$ ) picture, the RR vertex operator takes the form

$$
\begin{equation*}
V_{\mathcal{F}}=(2 \pi \alpha)^{3 / 2} \tilde{S}^{T} \mathcal{C} \mathcal{F} S e^{-\phi / 2} e^{-\tilde{\phi} / 2} \tag{2.1}
\end{equation*}
$$

where $\mathcal{F}:=\sum_{p} F_{\mu_{1} \cdots \mu_{p+1}} \Gamma^{\mu_{1} \cdots \mu_{p+1}} / p$ ! and $\mathcal{C}$ is the charge conjugation matrix ${ }^{3}$. Decomposing the spinor indices with respect to $\mathrm{SO}(4) \times \mathrm{SO}(6)$, we have

$$
\begin{equation*}
V_{\mathcal{F}}=(2 \pi \alpha)^{3 / 2} \mathcal{F}^{\alpha \beta A B} S_{\alpha} S_{A} \tilde{S}_{\beta} \tilde{S}_{B} e^{-\phi / 2} e^{-\tilde{\phi} / 2}+\cdots, \tag{2.3}
\end{equation*}
$$

where $\cdots$ denotes contributions from the components of $\mathcal{F}$ other than $\mathcal{F}^{\alpha \beta A B}$. Due to their different tensor structure, these components will not be relevant for our discussion.

To obtain the tensor structure of the deformation relations (1.1) or (1.4), it is necessary to consider a configuration of RR fields such that the only non-vanishing components are

[^1]\[

$$
\begin{equation*}
S=\left(2 \kappa_{10}^{2}\right)^{-1} \int d^{10} x \sqrt{g}\left(R-\frac{1}{2} F^{2}\right) . \tag{2.2}
\end{equation*}
$$

\]

the symmetric ones $\mathcal{F}^{(\alpha \beta)(A B)}$. Here $(\alpha \beta),(A B)$ represent symmetrization of the indices. This can be achieved by turning on the RR 5 -form configuration (1.7), (1.8). As a result

$$
\begin{equation*}
\mathcal{F}^{\alpha \beta A B}=f_{\mu \nu} g_{a b c}\left(\sigma^{\mu \nu}\right)^{\alpha \beta}\left(\Sigma^{a b c}\right)^{A B} \tag{2.4}
\end{equation*}
$$

where

$$
\begin{equation*}
\sigma^{\mu \nu}:=\frac{1}{4}\left(\sigma^{\mu} \bar{\sigma}^{\nu}-\sigma^{\nu} \bar{\sigma}^{\mu}\right), \quad \Sigma^{a b c}:=\Sigma^{[a} \bar{\Sigma}^{b} \Sigma^{c]} \tag{2.5}
\end{equation*}
$$

and they are self-dual:

$$
\begin{equation*}
\sigma^{\mu \nu}=\frac{1}{2!} \epsilon^{\mu \nu \rho \lambda} \sigma^{\rho \lambda}, \quad \Sigma^{a b c}=\frac{i}{3!} \epsilon^{a b c d e f} \Sigma^{d e f} \tag{2.6}
\end{equation*}
$$

in which $\sigma_{\mu}, \bar{\sigma}_{\mu}$ and $\Sigma^{a}, \bar{\Sigma}^{a}$ are gamma matrices for the 4-dimensional and the 6-dimensional spaces; one example of the basis is given in appendix.

The quantization of the string worldsheet coupled to the RR-fields leads to the nonanticommutative relations (1.1) and (1.4) 18-20, 23], and one expects the D3-brane worldvolume action to possess supersymmetry that is carried by the deformed superspace. The SYM action on the worldvolume of the D3-branes in the presence of a constant RR 5-form flux $\mathcal{F}^{(\alpha \beta)(A B)}$ satisfying the double self-dual condition (1.9) was computed in (25) using string perturbation theory. The deformation is determined by the parameters

$$
\begin{equation*}
C^{\alpha \beta A B}:=\left(2 \pi \alpha^{\prime}\right)^{3 / 2} \mathcal{F}^{\alpha \beta A B} \tag{2.7}
\end{equation*}
$$

which are kept fixed in the $\alpha^{\prime} \rightarrow 0$ limit. The action was computed up to the first order in $\mathcal{F}$. The worldvolume action possess $\mathcal{N}=(1 / 2,0)$ supersymmetry when $\mathcal{F}^{\alpha \beta A B}$ is of rank one in the $(A, B)$-space [25]. When it is of rank two in the $(A, B)$-space, one expects the worldvolume action to have $\mathcal{N}=(1,0)$ supersymmetry. An alternative way to construct the deformed supersymmetric action is to use deformed $\mathcal{N}=(1,1)$ harmonic superspace.

### 2.2 Non-anticommutative SYM with $\mathcal{N}=(1,0)$ supersymmetry

### 2.2.1 RR-flux configuration for $\mathcal{N}=(1,0)$ supersymmetry

To introduce a deformation to the $\mathcal{N}=(1,1)$ superspace, the RR-5 form $\mathcal{F}^{\alpha \beta A B}$ should be non-vanishing only for a $2 \times 2$ sub-block of the indices for $A, B$. This can be achieved with the following configuration of RR 5 -form:

$$
\begin{align*}
& F_{01456}=-i F_{01789}=F_{23456}=-i F_{23789}=c  \tag{2.8}\\
& F_{01786}=-i F_{01459}=F_{23786}=-i F_{23459}=c
\end{align*}
$$

where

$$
\begin{equation*}
c:=F_{01456} \tag{2.9}
\end{equation*}
$$

is a constant. The first or the second line of (2.8) is respectively a minimal configuration which satisfies (1.7), (1.8). By having this particular combination of these minimal configurations, $\mathcal{F}$ is given by

$$
\begin{align*}
\mathcal{F}^{\alpha \beta A B} & =24 c\left(\sigma^{01}+\sigma^{23}\right)^{\alpha \beta}\left(\Sigma^{456}+i \Sigma^{459}\right)^{A B} \\
& =24 i c\left(\tau^{3}\right)^{\alpha \beta} M^{A B} \tag{2.10}
\end{align*}
$$

and

$$
\begin{equation*}
M:=\Sigma^{456}+i \Sigma^{459} . \tag{2.11}
\end{equation*}
$$

To proceed further, one needs an explicit representation of the $\Sigma$-matrices. For example, one can identify the $\Sigma$-matrices here with the canonical choice of $\Sigma$-matrices (A.6) given in the appendix. For example if we take

$$
\begin{equation*}
\Sigma^{6,9,4,5,7,8}=\left(\Sigma^{4,5,6,7,8,9}\right)_{\text {appendix }}, \tag{2.12}
\end{equation*}
$$

then

$$
M=2 i\left(\begin{array}{cc}
\tau^{1} & 0  \tag{2.13}\\
0 & 0
\end{array}\right):=M_{0}
$$

which is of rank 2 . We remark that a different identification of the $\Sigma$-matrices gives a different $M$ that is related to (2.13) by a bi-unitary transformation

$$
\begin{equation*}
M=\tilde{V} M_{0} V, \tag{2.14}
\end{equation*}
$$

where $\tilde{V}=V^{T}, V$ are unitary. The transformation is bi-unitary since in general $\tilde{V} V \neq 1$. For example, for the identification

$$
\begin{equation*}
\Sigma^{6,9,4,5,7,8}=\left(\Sigma^{4,8,6,7,5,9}\right)_{\text {appendix }}, \tag{2.15}
\end{equation*}
$$

we have

$$
M=V^{T} 2 i\left(\begin{array}{cc}
\tau^{1} & 0  \tag{2.16}\\
0 & 0
\end{array}\right) V,
$$

with

$$
V=\frac{1}{\sqrt{2}}\left(\begin{array}{cc}
\tau^{1} & -\tau^{2}  \tag{2.1.1}\\
-\tau^{2} & \tau^{1}
\end{array}\right) .
$$

It is

$$
V^{T} V=-V V^{T}=-i\left(\begin{array}{cc}
0 & \tau^{3}  \tag{2.18}\\
\tau^{3} & 0
\end{array}\right) \neq 1
$$

and so the transformation (2.14) is not unitary, but a bi-unitary one. We note that the vertex operator with $M$ given by (2.14) is equivalent to the one with $M=M_{0}$ under a change of basis for the spin field $S_{A}, \tilde{S}_{A}$

$$
\begin{equation*}
S \rightarrow V S, \quad \tilde{S} \rightarrow V \tilde{S} \tag{2.19}
\end{equation*}
$$

Thus we have shown that by turning on the constant RR 5 -form field (2.8), $\mathcal{F}^{\alpha \beta A B}$ takes the factorized form (1.6) with $\operatorname{det} b \neq 0$, i.e. it is of rank 2 with respect to the $A, B$ indices.

### 2.2.2 Harmonic superspace and non-anticommutative SYM

Given the non-anticommutative relation (1.4), the deformed $\mathcal{N}=4$ action on the worldvolume of the D3-branes can be obtained as a supersymmetric action for the gauge superfield and hypermultiplet superfield of deformed harmonic superspace. Let us first give a brief
introduction to harmonic superspace 35. For a comprehensive review, we refer the reader to (36].

Let $\left(x^{\mu}, \theta_{i}^{\alpha}, \bar{\theta}^{\dot{\alpha} i}\right)$ be the coordinates of the $\mathcal{N}=(1,1)$ superspace, where $\mu=0,1,2,3$ are the spacetime indices, $\alpha, \dot{\alpha}=1,2$ spinor indices and $i=1,2$ are the indices of the $\mathrm{SU}(2)$ R-symmetry. The harmonic superspace is supplemented by the harmonic variables $u_{i}^{ \pm}$which form an $\mathrm{SU}(2)$ matrix:

$$
\begin{align*}
u^{i+} u_{i}^{-} & =1, \quad u^{+i} u_{i}^{+}=u^{-i} u_{i}^{-}=0,  \tag{2.20}\\
\widetilde{u^{+i}} & =u_{i}^{-} .
\end{align*}
$$

Here ${ }^{\sim}$ is the standard conjugation acting on the harmonic superspace. Its action on the other coordinates of the superspace is

$$
\begin{equation*}
\tilde{x}_{A}^{\mu}=x_{A}^{\mu}, \quad \widetilde{\theta^{ \pm \alpha}}=\varepsilon_{\alpha \beta} \theta^{ \pm \beta}, \quad \widetilde{\overline{\theta^{ \pm \dot{\alpha}}}}=\varepsilon_{\dot{\alpha} \dot{\beta}} \bar{\theta}^{ \pm \dot{\beta}} \tag{2.21}
\end{equation*}
$$

where

$$
\begin{array}{ll}
\theta_{\alpha}^{ \pm}:=u_{i}^{ \pm} \theta_{\alpha}^{i}, & \bar{\theta}_{\dot{\alpha}}^{ \pm}:=u_{i}^{ \pm} \bar{\theta}_{\dot{\alpha}}^{i}, \\
x_{A}^{\mu}=x^{\mu}-i\left(\theta^{+} \sigma^{\mu} \bar{\theta}^{-}+\theta^{-} \sigma^{\mu} \bar{\theta}^{+}\right) & \tag{2.22}
\end{array}
$$

is the analytic basis of the harmonic superspace. And as a result we have the condition on the parameters deforming the $\mathcal{N}=(1,1)$ superspace:

$$
\begin{equation*}
\widetilde{C^{\alpha \beta i j}}=C_{\alpha \beta i j} . \tag{2.23}
\end{equation*}
$$

Using these variables, one can introduce the harmonic projection of the supercovariant derivatives

$$
\begin{equation*}
D_{\alpha}^{ \pm}=u_{i}^{ \pm} D_{\alpha}^{i}, \quad \bar{D}_{\alpha}^{ \pm}=u_{i}^{ \pm} \bar{D}_{\alpha}^{i} . \tag{2.24}
\end{equation*}
$$

Instead of chiral superfields, one considers analytic superfields in harmonic superspace. They satisfy $D_{\alpha}^{+} \Phi=\bar{D}_{\dot{\alpha}}^{+} \Phi=0$. The supercharges and supercovariant derivatives take the form

$$
\begin{array}{ll}
Q_{\alpha}^{+}=\frac{\partial}{\partial \theta^{-\alpha}}-2 i \sigma_{\alpha \dot{\alpha}}^{\mu} \bar{\theta}^{+\dot{\alpha}} \frac{\partial}{\partial x_{A}^{\mu}}, & Q_{\alpha}^{-}=-\frac{\partial}{\partial \theta^{+\alpha}} \\
\bar{Q}_{\dot{\alpha}}^{+}=\frac{\partial}{\partial \bar{\theta}^{-\dot{\alpha}}}+2 i \theta^{+\alpha} \sigma_{\alpha \dot{\alpha}}^{\mu} \frac{\partial}{\partial x_{A}^{\mu}}, & \bar{Q}_{\dot{\alpha}}^{-}=-\frac{\partial}{\partial \bar{\theta}^{+\dot{\alpha}}}, \\
D_{\alpha}^{+}=\frac{\partial}{\partial \theta^{-\alpha}}, & D_{\alpha}^{-}=-\frac{\partial}{\partial \theta^{+\alpha}}+2 i \sigma_{\alpha \dot{\alpha}}^{\mu} \bar{\theta}^{-\dot{\alpha}} \frac{\partial}{\partial x_{A}^{\mu}}, \\
\bar{D}_{\dot{\alpha}}^{+}=\frac{\partial}{\partial \bar{\theta}^{-\dot{\alpha}}}, & \bar{D}_{\dot{\alpha}}^{-}=-\frac{\partial}{\partial \bar{\theta}^{+\dot{\alpha}}}-2 i \theta^{-\alpha} \sigma_{\alpha \dot{\alpha} \dot{\alpha}}^{\mu} \frac{\partial}{\partial x_{A}^{\mu}},
\end{array}
$$

in terms of which the condition for the analytic superfield can be solved easily and is of the form

$$
\begin{equation*}
\Phi=\Phi\left(x_{A}^{\mu}, \theta^{+}, \bar{\theta}^{+}, u\right) . \tag{2.26}
\end{equation*}
$$

One can expand the analytic superfield in $\theta$ and obtain a finite expansion with coefficients being functions of $x_{A}$ and $u$. Each $\theta$-component can be further expanded in terms of
symmetrized products of $u^{+}$and $u^{-}$. This second expansion is infinite and so each analytic superfield contains an infinite number of component fields.

It is convenient to introduce covariant derivatives with respect to $u^{ \pm}$compatible with the defining relations (2.20)

$$
\begin{array}{rlr}
D^{++} & =u^{+i} \frac{\partial}{\partial u^{-i}}, & D^{--}=u^{-i} \frac{\partial}{\partial u^{+i}}, \\
D^{0} & =u^{+i} \frac{\partial}{\partial u^{+i}}-u^{-i} \frac{\partial}{\partial u^{-i}} . & \tag{2.27}
\end{array}
$$

The operator $D^{0}$ measures the $\mathrm{U}(1)$ charges of the harmonics $u^{ \pm}$. A function of charge $q$ satisfies

$$
\begin{equation*}
D^{0} \phi^{(q)}=q \phi^{(q)} \tag{2.28}
\end{equation*}
$$

and admits the expansion (here $q \geq 0$; for $q<0$ there is an analogous formula)

$$
\begin{equation*}
\phi^{(q)}(u)=\sum_{n=0}^{\infty} \phi^{\left(i_{1} \cdots i_{q+n} j_{1} \cdots j_{n}\right)} u_{\left(i_{1}\right.}^{+} \cdots u_{i_{q+n}}^{+} u_{j_{1}}^{-} \cdots u_{\left.j_{n}\right)}^{-} . \tag{2.29}
\end{equation*}
$$

The coefficients $\phi^{i_{1} \cdots j_{m}}$ are irreducible $\mathrm{SU}(2)$ tensors with isospin $(n+m) / 2$.
The non-anticommutative $\mathcal{N}=(1,1)$ superspace has the deformed relation

$$
\left\{\theta^{\alpha i}, \theta^{\beta j}\right\}=C^{\alpha \beta i j}, \quad i=1,2 .
$$

The deformation is equivalent to a $*$-product

$$
\begin{equation*}
(f * g)(\theta)=f(\theta) \exp \left(-\frac{1}{2} \frac{\overleftarrow{\partial}}{\partial \theta_{i}^{\alpha}} C_{i j}^{\alpha \beta} \frac{\vec{\partial}}{\partial \theta_{j}^{\beta}}\right) g(\theta) \tag{2.31}
\end{equation*}
$$

In the harmonic superspace approach, the $\mathcal{N}=2$ gauge multiplet is described by a charge 2 analytic superfield $V^{++}=V^{++M} T^{M}$ where $T^{M}$ are the Lie algebra generators. We will consider $\mathrm{U}(N)$ in this paper. Under the deformed $\mathrm{U}(N)$ gauge group, the gauge multiplet transforms as

$$
\begin{equation*}
\delta_{\Lambda} V^{++}=-D^{++} \Lambda+i\left[V^{++} \stackrel{*}{,} \Lambda\right] \tag{2.32}
\end{equation*}
$$

where $\Lambda$ is an analytic superfield parameter. The action of $\mathcal{N}=2$ SYM is given by [37, 21]

$$
\begin{equation*}
S_{V}=\frac{1}{2} \sum_{n=2}^{\infty} \frac{(-i)^{n}}{n} \operatorname{tr} \int d^{12} z d u_{1} \cdots d u_{n} \frac{V^{++}\left(z, u_{1}\right) * V^{++}\left(z, u_{2}\right) * \cdots * V^{++}\left(z, u_{n}\right)}{\left(u_{1}^{+} u_{2}^{+}\right)\left(u_{2}^{+} u_{3}^{+}\right) \cdots\left(u_{n}^{+} u_{1}^{+}\right)}, \tag{2.33}
\end{equation*}
$$

where $z=\left(x, \theta_{i}^{\alpha}, \bar{\theta}_{i}^{\dot{\alpha}}\right)$.
As for the hypermultiplet, it can be described either by a complex analytic superfield $q^{+}$with $\mathrm{U}(1)$ charge +1 or by a real analytic neutral superfield $\omega$. These descriptions are known to be related to each other via a duality [36] and one can restrict to either description. Similar consideration applies in the deformed case. To construct the deformed $\mathcal{N}=4 \mathrm{SYM}$, let us consider $q^{+}$in the adjoint representation. The coupling of $q^{+}$to the $\mathcal{N}=2$ gauge multiplet is given by

$$
\begin{equation*}
S_{q}=-\int d \zeta d u \operatorname{Tr} \bar{q}^{+} *\left(D^{++}+i\left[V^{++}, q^{+}\right]\right) \tag{2.34}
\end{equation*}
$$

where

$$
\begin{equation*}
d \zeta:=d^{4} x_{A} d^{4} \theta^{-} . \tag{2.35}
\end{equation*}
$$

The $\mathcal{N}=4$ SYM theory can be written down in terms of these $\mathcal{N}=2$ superfields. In fact, by using an $\mathcal{N}=2$ gauge multiplet and an $\mathcal{N}=2$ hypermultiplet $q^{+}$in the adjoint representation, the $\mathcal{N}=4$ action can be written as

$$
\begin{equation*}
S_{\mathrm{SYM}}=S_{V}+S_{q} . \tag{2.36}
\end{equation*}
$$

For a generic non-singlet deformation (1.6) with generic $b$ such that $\operatorname{det} b \neq 0$, the theory has $\mathcal{N}=(1,0)$ supersymmetry.

The action (2.36) is written in terms of $\mathcal{N}=(1,1)$ superfields. To rewrite it in terms of component fields, one needs to substitute the component expansion of the superfield and carry out the integrals in $\theta$ and $u$. As we remarked above, the component expansion of an analytic superfield contains an infinite number of component fields and auxiliary fields. However many of these can be gauged away. For example, one can utilize the infinite degrees of freedom present in the analytic gauge parameter $\Lambda$ to eliminate all the auxiliary fields in the gauge superfield $V^{++}$. In the Wess-Zumino gauge, $V_{\mathrm{WZ}}^{++}$has only a finite number of physical components [21]. For the hypermultiplet superfield $q^{+}$, the auxiliary fields can be eliminated from the action using the classical equation of motion for $q^{+}$. We refer the reader to [21] for the case of a $\mathrm{U}(1)$ gauge group. The generalization to $\mathrm{U}(N)$ is straightforward.

Although the resulting component action is manifest in supersymmetry, the gauge transformations of the component fields are typically obscured and become non-canonical. This was first observed in [12] for the deformed $\mathcal{N}=(1 / 2,1 / 2)$ superspace. To obtain component fields which have canonical gauge transformations, one must perform a field redefinition. The redefined component fields admit canonical gauge transformations, but their supersymmetry transformations are deformed. This can be worked out explicitly and fully in the deformed $\mathcal{N}=(1 / 2,1 / 2)$ case. However this becomes much more complicated for the deformed $\mathcal{N}=(1,1)$ case [27, 28, 23, 30]. Both the field redefinition and the deformed supersymmetry transformations involve infinite series expansions in the deformation parameter. Therefore although there is in principle no difficulty to write down the deformed action explicitly, the procedure is rather involved and we will not carry out its evaluation here.

### 2.3 Non-anticommutative SYM with $\mathcal{N}=(1 / 2,0)$ supersymmetry

To construct a deformation of the $\mathcal{N}=4$ SYM theory with $\mathcal{N}=(1 / 2,0)$ supersymmetry, one can first write the $\mathcal{N}=4$ theory in terms of $\mathcal{N}=(1 / 2,1 / 2)$ superfields and then introduces non-anticommutative deformation to the $\mathcal{N}=(1 / 2,1 / 2)$ superspace. In this case, the RR-5 form $\mathcal{F}^{\alpha \beta A B}$ should be non-vanishing only for a $1 \times 1$ sub-block of the indices for $A, B$.

This can be achieved by turning on further components in addition to those in (2.8) which has the effect of further reducing the rank of $\mathcal{F}^{\alpha \beta A B}$. Up to equivalence, the appro-
priate RR 5 -form configuration is

$$
\begin{align*}
& F_{01456}=-i F_{01789}=F_{23456}=-i F_{23789}=c \\
& F_{01786}=-i F_{01459}=F_{23786}=-i F_{23459}=c  \tag{2.37}\\
& F_{01476}=i F_{01589}=F_{23476}=i F_{23589}=i c \\
& F_{01586}=i F_{01479}=F_{23586}=i F_{23479}=-i c
\end{align*}
$$

where

$$
\begin{equation*}
c:=F_{01456} \tag{2.38}
\end{equation*}
$$

is a constant. The matrix $\mathcal{F}$ takes the form

$$
\begin{equation*}
\mathcal{F}^{\alpha \beta A B}=24 i c\left(\tau^{3}\right)^{\alpha \beta} M^{A B} \tag{2.39}
\end{equation*}
$$

where in this case $M^{A B}$ is given by

$$
\begin{equation*}
M:=\Sigma^{456}+i \Sigma^{459}+i\left(\Sigma^{476}+i \Sigma^{479}\right) \tag{2.40}
\end{equation*}
$$

Without loss of generality, we take the same identification of $\Sigma$-matrices as in (2.12) to obtain

$$
\begin{equation*}
M=4 i U^{T} M_{0} U \tag{2.41}
\end{equation*}
$$

where

$$
M_{0}=\left(\begin{array}{llll}
1 & 0 & 0 & 0  \tag{2.42}\\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{array}\right) \quad \text { and } \quad U=\frac{1}{\sqrt{2}}\left(\begin{array}{cccc}
1 & 1 & 0 & 0 \\
-1 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right)
$$

As before, the presence of $U$ is a matter of choice of basis and can be absorbed by a transformation of the spin fields. Therefore the configuration (2.37) of the RR 5-form flux gives rise to a deformation that is governed by 2.39 with $M$ of rank 1 , and corresponds to a non-anticommutative deformation of the $\mathcal{N}=(1 / 2,1 / 2)$ superspace.

As mentioned above, the non-anticommutative deformed SYM theory can be obtained easily using the deformed $\mathcal{N}=1$ superspace. The theory admits $\mathcal{N}=(1 / 2,0)$ supersymmetry. It is interesting to note that the additional terms in the action which deform the theory have an interpretation as the Chern-Simons couplings of the D3-brane to a certain constant RR 5-form background 38.

## 3. The supergravity solution

It is easy to check that the constant RR 5-form field strength (2.8) does not generate any energy-momentum tensor in flat Euclidean space:

$$
\begin{equation*}
T_{M N}=F_{M M_{1} M_{2} M_{3} M_{4}} F_{N}^{M_{1} M_{2} M_{3} M_{4}}-\frac{1}{10} g_{M N} F^{2}=0 \tag{3.1}
\end{equation*}
$$

However this is no longer the case once one takes into account the backreaction of the $N$ D3-branes, which turns the flat spacetime to $A d S_{5} \times S^{5}$. Our goal now is to construct the supergravity solution which would give rise to the components (2.8) for the RR 5-form field on the worldvolume of the $N$ D3-branes. Moreover, as a deformation, the solution should reduce back to the original $A d S_{5} \times S^{5}$ background when the deformation is turned off.

### 3.1 Supergravity dual for the $\mathcal{N}=(1,0)$ case

In order to obtain the desired configuration (2.8) of the RR 5-form flux, we consider the following configuration of intersecting D3-branes,


Here $D 3_{1}$ denotes the original $N$ D3-branes; and we have introduced four additional sets of D3-branes. Let us check supersymmetry. In type IIB string theory, the two supersymmetries $\varepsilon_{1}, \varepsilon_{2}$ are of the same chirality. The set of $N$ D3-branes imposes the condition

$$
\begin{equation*}
\Gamma^{0123} \varepsilon_{1}=\varepsilon_{2} . \tag{3.3}
\end{equation*}
$$

This condition relates the two supersymmetries and hence reduces the supersymmetry by one half. Now introduce the other 4 sets of branes $D 3_{2}, D 3_{2^{\prime}}, D 3_{3}, D 3_{3^{\prime}}$. This imposes additionally the conditions

$$
\begin{equation*}
\Gamma^{0145} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{0178} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2345} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2378} \varepsilon_{1}=\varepsilon_{2} . \tag{3.4}
\end{equation*}
$$

The 4 conditions in (3.4) are not all independent. In fact there are only 3 independent equations in (3.4) and (3.4) is equivalent to the following system:

$$
\begin{equation*}
\Gamma^{2378} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{0123} \varepsilon_{1}=-\varepsilon_{1}, \quad \Gamma^{4578} \varepsilon_{1}=-\varepsilon_{1} \tag{3.5}
\end{equation*}
$$

Together with (3.3), we see that generically our set of intersecting branes preserves $1 / 16$ of the type IIB supersymmetry, i.e. 2 supersymmetries are preserved. However in the near horizon limit of the $N$ D3-branes, the condition (3.3) is lifted and all the 32 supersymmetries are preserved. Therefore, in this limit, we only have the conditions (3.5). The first of these conditions gives $\varepsilon_{2}$ once $\varepsilon_{1}$ is solved. The second and the third conditions in (3.5) impose 2 conditions on $\varepsilon_{1}$ which means 4 supersymmetries are preserved. Moreover the 4 supersymmetries are chiral both in the 4 -dimensional and in the 6 -dimensional sense. Hence we can denote the preserved supersymmetries by

$$
\begin{equation*}
\varepsilon^{\alpha A}, \quad \alpha=1,2 ; \quad A=1,2 . \tag{3.6}
\end{equation*}
$$

This matches precisely with the preserved $\mathcal{N}=(1,0)$ supersymmetries in the non-anticommutative SYM theory.

The metric of our intersecting branes system is given by

$$
\begin{align*}
d s^{2}= & \sqrt{\frac{H_{3} H_{3^{\prime}}}{H_{1} H_{2} H_{2^{\prime}}}}\left(d x_{0}^{2}+d x_{1}^{2}\right)+\sqrt{\frac{H_{2} H_{2^{\prime}}}{H_{1} H_{3} H_{3^{\prime}}}}\left(d x_{2}^{2}+d x_{3}^{2}\right)+\sqrt{\frac{H_{1} H_{2^{\prime}} H_{3^{\prime}}}{H_{2} H_{3}}}\left(d x_{4}^{2}+d x_{5}^{2}\right) \\
& +\sqrt{\frac{H_{1} H_{2} H_{3}}{H_{2^{\prime}} H_{3^{\prime}}}}\left(d x_{7}^{2}+d x_{8}^{2}\right)+\sqrt{H_{1} H_{2} H_{3} H_{2^{\prime}} H_{3^{\prime}}}\left(d x_{6}^{2}+d x_{9}^{2}\right) \tag{3.7}
\end{align*}
$$

and the RR 5 -form is

$$
\begin{equation*}
F=F_{0}+F_{1}, \tag{3.8}
\end{equation*}
$$

where

$$
\begin{align*}
& F_{0}:=d\left(\frac{1}{H_{1}}\right) d x^{0123}+\text { dual, }  \tag{3.9}\\
& F_{1}:=d\left(\frac{1}{H_{2}}\right) d x^{0145}+d\left(\frac{1}{H_{2^{\prime}}}\right) d x^{0178}+d\left(\frac{1}{H_{3}}\right) d x^{2345}+d\left(\frac{1}{H_{3^{\prime}}}\right) d x^{2378}+\text { dual. } \tag{3.10}
\end{align*}
$$

$F_{0}$ is the RR 5 -form sourced by the original set of $N \mathrm{D} 3$-branes, and $F_{1}$ is sourced by the additional sets of branes.

In order that no components of the RR 5-form other than those that are present in (2.8) are activated, we choose the harmonic functions $H_{2}, H_{2^{\prime}}, H_{3}, H_{3^{\prime}}$ to be functions of $x_{6}$ and $x_{9}$ only. Moreover to produce the complex structure of the RR 5 -form in the equation (2.8), it is necessary that $H_{2}$ and $H_{2^{\prime}}$ depend on $x_{6}, x_{9}$ in a particular way:

$$
\begin{equation*}
H_{2}=H_{2}(z), \quad H_{2^{\prime}}=H_{2^{\prime}}(z), \quad H_{3}=H_{3}(z), \quad H_{3^{\prime}}=H_{3^{\prime}}(z) \tag{3.11}
\end{equation*}
$$

where

$$
\begin{equation*}
z=x_{6}+i x_{9} \tag{3.12}
\end{equation*}
$$

is a complex variable. In other word, the branes $D 3_{2}, D 3_{2^{\prime}}, D 3_{3}, D 3_{3^{\prime}}$ are smeared and have effectively a single transverse direction.

The equations of motion for this system of partially localised intersecting branes are given by the curved space Laplace equations (39]

$$
\begin{align*}
&\left(H_{2} H_{3} \partial_{i}^{2}+H_{2^{\prime}} H_{3^{\prime}} \partial_{m}^{2}+\partial_{a}^{2}\right) H_{1}=0,  \tag{3.13}\\
& \partial_{a}\left(\frac{H_{2}^{2}}{H_{3^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{2}}\right)\right)=0,  \tag{3.14}\\
& \partial_{a}\left(\frac{H_{2^{\prime}}^{2}}{H_{3}^{2}} \partial_{a}\left(\frac{1}{H_{2^{\prime}}}\right)\right)=0,  \tag{3.15}\\
& \partial_{a}\left(\frac{H_{3}^{2}}{H_{2^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{3}}\right)\right)=0,  \tag{3.16}\\
& \partial_{a}\left(\frac{H_{3^{\prime}}^{2}}{H_{2}^{2}} \partial_{a}\left(\frac{1}{H_{3^{\prime}}}\right)\right)=0, \tag{3.17}
\end{align*}
$$

where we have used $i=4,5$ to denote the indices in the $x_{4}, x_{5}$ directions and $\partial_{i}^{2}:=\partial_{4}^{2}+\partial_{5}^{2}$ is the 2-dimensional flat Laplacian. Similarly $\partial_{m}^{2}:=\partial_{7}^{2}+\partial_{8}^{2}$ and $\partial_{a}^{2}:=\partial_{6}^{2}+\partial_{9}^{2}$. Due to (3.11), the equations (3.14)-(3.17) are satisfied immediately. Since the branes $D 3_{2}, D 3_{2^{\prime}}, D 3_{3}, D 3_{3^{\prime}}$ are smeared and have effectively a single transverse direction, the charge associated with them is well defined only if $F_{1}$ as given by (3.10) is well-defined at $|z|=\infty$. Moreover we would like to reproduce the components of the RR flux precisely at the worldvolume of the set of $N$ D3-branes, i.e. at $x_{4}=x_{5}=x_{6}=x_{7}=x_{8}=x_{9}=0$. We obtain the unique solution

$$
\begin{equation*}
H_{2}=H_{2^{\prime}}=H_{3}=H_{3^{\prime}}=\frac{1}{1+c z} . \tag{3.18}
\end{equation*}
$$

In this case, the RR 5-form field strength (3.10) is actually constant and equal to (2.8) everywhere.

Finally the equation for $H_{1}$ reduces to

$$
\begin{equation*}
\left(\partial_{i}^{2}+\partial_{m}^{2}+\frac{1}{H_{2}^{2}} \partial_{a}^{2}\right) H_{1}=0 \tag{3.19}
\end{equation*}
$$

Naively one may try to treat $c$ as a small parameter and solve (3.19) by solving the differential equation perturbatively. This is messy however. A much simpler way to solve ( 3.19 ) in closed form is due to the following observation. We first rewrite the Laplacian $\partial_{a}^{2}=4 \partial_{z} \partial_{\bar{z}}$ where $\bar{z}:=x_{6}-i x_{9}$ and introduce

$$
\begin{equation*}
w:=\int H_{2}^{2} d z=\frac{z}{1+c z} \tag{3.20}
\end{equation*}
$$

where we have chosen the integration constant such that $w=0$ when $z=0$. In terms of $w$ and $\bar{z}$, the equation (3.19) can be rewritten as

$$
\begin{equation*}
\left(\partial_{i}^{2}+\partial_{m}^{2}+4 \partial_{w} \partial_{\bar{z}}\right) H_{1}=0 \tag{3.21}
\end{equation*}
$$

Except for the fact that $w$ is not the complex conjugate of $\bar{z}$, this is formally the same Laplace equation as in the undeformed $A d S_{5} \times S^{5}$ case. This fact allows us to solve (3.21) easily. We obtain

$$
\begin{equation*}
H_{1}=1+\frac{R^{4}}{\rho^{4}} \tag{3.22}
\end{equation*}
$$

where

$$
\begin{equation*}
\frac{R^{4}}{\alpha^{\prime 2}}:=4 \pi g_{s} N=\lambda \tag{3.23}
\end{equation*}
$$

and

$$
\begin{equation*}
\rho^{2}:=x_{i}^{2}+x_{m}^{2}+w \bar{z} \tag{3.24}
\end{equation*}
$$

It is

$$
\begin{equation*}
\rho^{2}=x_{i}^{2}+x_{m}^{2}+\frac{z \bar{z}}{1+c z}=x_{i}^{2}+x_{m}^{2}+\frac{w \bar{w}}{1-\bar{c} \bar{w}} \tag{3.25}
\end{equation*}
$$

Formally the solution $H_{1}$ takes the same form as the undeformed one. That this is true is because the differential algebra involved does not care about the complex structure. Using the above results, the metric becomes

$$
\begin{equation*}
d s^{2}=\frac{1}{\sqrt{H_{1}}}\left(d x_{0}^{2}+d x_{1}^{2}+d x_{2}^{2}+d x_{3}^{2}\right)+\sqrt{H_{1}}\left(d x_{4}^{2}+d x_{5}^{2}+d x_{7}^{2}+d x_{8}^{2}+\frac{d z d \bar{z}}{(1+c z)^{2}}\right) \tag{3.26}
\end{equation*}
$$

It is clear that the singularity at $z=-1 / c$ is infinitely far away and so the supergravity background is regular. We also remark that although the metric is invariant under $\mathrm{SO}(4)$ rotations in $x^{\mu}, \mu=0,1,2,3$, the Euclidean Lorentzian symmetry $\mathrm{SO}(4)$ is broken by the RR 5-form. This agrees with the field theory.

Summarizing, our proposal is that the non-anticommutative SYM theory with deformation parameter (2.7), (2.8) is dual to the near horizon limit of the supergravity background given by the intersecting brane system (3.2). The near horizon limit is taken with

$$
\begin{equation*}
\tilde{x}^{a}:=x^{a} / \alpha^{\prime} \tag{3.27}
\end{equation*}
$$

fixed in the $\alpha^{\prime} \rightarrow 0$ limit. Introducing

$$
\begin{equation*}
U:=\rho / \alpha^{\prime} \tag{3.28}
\end{equation*}
$$

and also scaling $c$ such that

$$
\begin{equation*}
\tilde{c}:=\alpha^{\prime} c=\alpha^{\prime} F_{01456} \tag{3.29}
\end{equation*}
$$

is fixed in the $\alpha^{\prime} \rightarrow 0$ limit, we obtain the near horizon metric

$$
\begin{equation*}
\frac{d s^{2}}{\alpha^{\prime}}=\frac{U^{2}}{\sqrt{\lambda}} d x_{\mu}^{2}+\frac{\sqrt{\lambda}}{U^{2}}\left(d \tilde{x}_{4}^{2}+d \tilde{x}_{5}^{2}+d \tilde{x}_{7}^{2}+d \tilde{x}_{8}^{2}+\frac{d \tilde{z} d \overline{\tilde{z}}}{(1+\tilde{c} \tilde{z})^{2}}\right) \tag{3.30}
\end{equation*}
$$

where $\tilde{z}:=z / \alpha^{\prime}$, and

$$
\begin{equation*}
U^{2}=\tilde{x}_{i}^{2}+\tilde{x}_{m}^{2}+\frac{\tilde{z} \overline{\tilde{z}}}{1+\tilde{c} \tilde{z}} . \tag{3.31}
\end{equation*}
$$

The RR 5 -form is

$$
\begin{equation*}
F=F_{0}+F_{1}, \tag{3.32}
\end{equation*}
$$

where

$$
\begin{equation*}
\frac{F_{0}}{\alpha^{\prime 2}}=d\left(\frac{U^{4}}{\lambda}\right) d x^{0123}+\text { dual } \tag{3.33}
\end{equation*}
$$

and

$$
\begin{align*}
\frac{F_{1}}{\alpha^{\prime 2}}= & \tilde{c}\left(d x^{0} d x^{1} d \tilde{x}^{4} d \tilde{x}^{5} d \tilde{x}^{6}+i d x^{0} d x^{1} d \tilde{x}^{7} d \tilde{x}^{8} d \tilde{x}^{9}+d x^{2} d x^{3} d \tilde{x}^{4} d \tilde{x}^{5} d \tilde{x}^{6}+i d x^{2} d x^{3} d \tilde{x}^{7} d \tilde{x}^{8} d \tilde{x}^{9}\right. \\
& \left.+i d x^{0} d x^{1} d \tilde{x}^{4} d \tilde{x}^{5} d \tilde{x}^{9}+d x^{0} d x^{1} d \tilde{x}^{7} d \tilde{x}^{8} d \tilde{x}^{6}+i d x^{2} d x^{3} d \tilde{x}^{4} d \tilde{x}^{5} d \tilde{x}^{9}+d x^{2} d x^{3} d \tilde{x}^{7} d \tilde{x}^{8} d \tilde{x}^{6}\right) \\
& + \text { dual. } \tag{3.34}
\end{align*}
$$

Note that $F_{1}$ is well defined in the same limit (3.29) where the metric has a well-defined limit. Note also that the conditions (3.29) and (2.7) are indeed the same due to different normalization.

We remark that the RR-flux is necessarily complex in order to generate the nonanticommutative deformation. This is also reflected in the complexification of the metric through (3.35). We also remark that the effect of turning on the deformation (2.8) in the gauge theory is a simple replacement

$$
\begin{equation*}
d z d \bar{z} \rightarrow d w d \bar{z} \tag{3.35}
\end{equation*}
$$

in the metric of the supergravity dual. It is remarkable that the effects of non-anticommutativity can be summarized nicely in such a compact form through a simple change of variables. We will further comment on this in the discussion section.

### 3.2 Supergravity dual for the $\mathcal{N}=(1 / 2,0)$ case

To obtain the configuration (2.37) of the RR 5-form flux, we consider the following configuration of intersecting D3-branes,

| 1 | ( $\begin{array}{lllll}0 & 1 & 2 & 3\end{array}$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | ( 0 | 1 |  |  |  |
| $2^{\prime}$ | ( 0 | 1 |  |  | $8)$ |
| 3 | ( |  | 23 |  |  |
| $D 3_{3^{\prime}}$ | ( |  | 3 |  | - |
|  | ( 0 | 1 |  |  |  |
| D |  | 1 |  |  | 8 |
|  |  |  | , |  |  |
| $D 3_{5}$ |  |  | 23 |  | 8 ) |

Here $D 3_{1}$ denotes the original $N$ D3-branes; and we have introduced eight additional sets of D3-branes. The checking of supersymmetry is similar as before. We have from the original $N$ D3-branes the condition

$$
\begin{equation*}
\Gamma^{0123} \varepsilon_{1}=\varepsilon_{2} \tag{3.37}
\end{equation*}
$$

and the conditions

$$
\begin{align*}
& \Gamma^{0145} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{0178} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2345} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2378} \varepsilon_{1}=\varepsilon_{2},  \tag{3.38}\\
& \Gamma^{0147} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{0185} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2347} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{2385} \varepsilon_{1}=\varepsilon_{2}, \tag{3.39}
\end{align*}
$$

from the additional sets of branes. In the near horizon limit, this is equivalent to

$$
\begin{equation*}
\Gamma^{2378} \varepsilon_{1}=\varepsilon_{2}, \quad \Gamma^{0123} \varepsilon_{1}=-\varepsilon_{1}, \quad \Gamma^{4578} \varepsilon_{1}=-\varepsilon_{1} \tag{3.40}
\end{equation*}
$$

and

$$
\begin{equation*}
\Gamma^{48} \varepsilon_{1}=\varepsilon_{1} \tag{3.41}
\end{equation*}
$$

The presence of the additional projection condition (3.41) reduces further the unbroken supersymmetry to a single two-component chiral spinor and we can denote it as

$$
\begin{equation*}
\varepsilon^{\alpha}, \quad \alpha=1,2 \tag{3.42}
\end{equation*}
$$

Therefore, in the near horizon limit, the intersecting branes configuration preserves $1 / 16$ of the type IIB supersymmetry, i.e. 2 supersymmetries. This matches precisely with the $\mathcal{N}=(1 / 2,0)$ supersymmetries in the non-anticommutative SYM theory.

The metric of our intersecting branes system is given by

$$
\begin{align*}
d s^{2}= & \sqrt{\frac{H_{3} H_{3^{\prime}} H_{5} H_{5^{\prime}}}{H_{1} H_{2} H_{2^{\prime}} H_{4} H_{4^{\prime}}}}\left(d x_{0}^{2}+d x_{1}^{2}\right)+\sqrt{\frac{H_{2} H_{2^{\prime}} H_{4} H_{4^{\prime}}}{H_{1} H_{3} H_{3^{\prime}} H_{5} H_{5^{\prime}}}}\left(d x_{2}^{2}+d x_{3}^{2}\right) \\
& +\sqrt{\frac{H_{1} H_{2^{\prime}} H_{3^{\prime}} H_{4^{\prime}} H_{5^{\prime}}}{H_{2} H_{3} H_{4} H_{5}}} d x_{4}^{2}+\sqrt{\frac{H_{1} H_{2^{\prime}} H_{3^{\prime}} H_{4} H_{5}}{H_{2} H_{3} H_{4^{\prime}} H_{5^{\prime}}}} d x_{5}^{2} \\
& +\sqrt{\frac{H_{1} H_{2} H_{3} H_{4^{\prime}} H_{5^{\prime}}}{H_{2^{\prime}} H_{3^{\prime}} H_{4} H_{5}}} d x_{7}^{2}+\sqrt{\frac{H_{1} H_{2} H_{3} H_{4} H_{5}}{H_{2^{\prime}} H_{3^{\prime}} H_{4^{\prime}} H_{5^{\prime}}}} d x_{8}^{2} \\
& +\sqrt{H_{1} H_{2} H_{3} H_{4} H_{5} H_{2^{\prime}} H_{3^{\prime}} H_{4^{\prime}} H_{5^{\prime}}\left(d x_{6}^{2}+d x_{9}^{2}\right)} \tag{3.43}
\end{align*}
$$

and the RR 5 -form is

$$
\begin{equation*}
F=F_{0}+F_{1}, \tag{3.44}
\end{equation*}
$$

where

$$
\begin{align*}
F_{0}:= & d\left(\frac{1}{H_{1}}\right) d x^{0123}+\text { dual }  \tag{3.45}\\
F_{1}:= & d\left(\frac{1}{H_{2}}\right) d x^{0145}+d\left(\frac{1}{H_{2^{\prime}}}\right) d x^{0178}+d\left(\frac{1}{H_{3}}\right) d x^{2345}+d\left(\frac{1}{H_{3^{\prime}}}\right) d x^{2378}  \tag{3.46}\\
& +d\left(\frac{1}{H_{4}}\right) d x^{0147}+d\left(\frac{1}{H_{4^{\prime}}}\right) d x^{0158}+d\left(\frac{1}{H_{5}}\right) d x^{2347}+d\left(\frac{1}{H_{5^{\prime}}}\right) d x^{2358}+\text { dual. }
\end{align*}
$$

$F_{0}$ is the RR 5 -form sourced by the original set of $N$ D3-branes, and $F_{1}$ is sourced by the additional sets of branes. As before, we need to choose the functions $H_{2}, H_{2^{\prime}}, H_{3}, H_{3^{\prime}}$, $H_{4}, H_{4^{\prime}}, H_{5}, H_{5^{\prime}}$ to be functions of $z=x_{6}+i x_{9}$ only.

The equations of motion for the system are:

$$
\begin{align*}
&\left(H_{2} H_{3}\left(H_{4} H_{5} \partial_{4}^{2}+H_{4^{\prime}} H_{5^{\prime}} \partial_{5}^{2}\right)+H_{2^{\prime}} H_{3^{\prime}}\left(H_{4} H_{5} \partial_{7}^{2}+H_{4^{\prime}} H_{5^{\prime}} \partial_{8}^{2}\right)+\partial_{a}^{2}\right) H_{1}=0,  \tag{3.47}\\
& \partial_{a}\left(\frac{H_{4} H_{4^{\prime}}}{H_{5} H_{5^{\prime}}} \frac{H_{2}^{2}}{H_{3^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{2}}\right)\right)=0,  \tag{3.48}\\
& \partial_{a}\left(\frac{H_{4} H_{4^{\prime}}}{H_{5} H_{5^{\prime}}} \frac{H_{2^{\prime}}^{2}}{H_{3}^{2}} \partial_{a}\left(\frac{1}{H_{2^{\prime}}}\right)\right)=0,  \tag{3.49}\\
& \partial_{a}\left(\frac{H_{5} H_{5^{\prime}}}{H_{4} H_{4^{\prime}}} \frac{H_{3}^{2}}{H_{2^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{3}}\right)\right)=0,  \tag{3.50}\\
& \partial_{a}\left(\frac{H_{5} H_{5^{\prime}}^{\prime}}{H_{4} H_{4^{\prime}}} \frac{H_{3^{\prime}}^{2}}{H_{2}^{2}} \partial_{a}\left(\frac{1}{H_{3^{\prime}}}\right)\right)=0,  \tag{3.51}\\
& \partial_{a}\left(\frac{H_{2} H_{2^{\prime}}}{H_{3} H_{3^{\prime}}} \frac{H_{4}^{2}}{H_{5^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{4}}\right)\right)=0,  \tag{3.52}\\
& \partial_{a}\left(\frac{H_{2} H_{2^{\prime}}}{H_{3} H_{3^{\prime}}} \frac{H_{4^{\prime}}^{2}}{H_{5}^{2}} \partial_{a}\left(\frac{1}{H_{4^{\prime}}}\right)\right)=0,  \tag{3.53}\\
& \partial_{a}\left(\frac{H_{3} H_{3^{\prime}}}{H_{2} H_{2^{\prime}}} \frac{H_{5}^{2}}{H_{4^{\prime}}^{2}} \partial_{a}\left(\frac{1}{H_{5}}\right)\right)=0,  \tag{3.54}\\
& \partial_{a}\left(\frac{H_{3} H_{3^{\prime}}}{H_{2} H_{2^{\prime}}} \frac{H_{5^{\prime}}^{2}}{H_{4}^{2}} \partial_{a}\left(\frac{1}{H_{5^{\prime}}}\right)\right)=0, \tag{3.55}
\end{align*}
$$

where $a=6,9$. The equations (3.48) - (3.55) are satisfied immediately. As before, since the additional sets of branes are smeared and have effectively a single transverse direction, the charge associated with them is well defined only if $F_{1}$ as given by (3.46) is well-defined at $|z|=\infty$. Moreover we want to reproduce the components (2.37) of the RR flux precisely at the worldvolume of the set of $N$ D3-branes. We obtain the unique solution

$$
\begin{align*}
H_{2} & =H_{2^{\prime}}=H_{3}=H_{3^{\prime}}=\frac{1}{1+c z} \\
H_{4} & =H_{5}=\frac{1}{1+i c z} \\
H_{4^{\prime}} & =H_{5^{\prime}}=\frac{1}{1-i c z} \tag{3.56}
\end{align*}
$$

The RR 5 -form field strength (3.46) is constant and equal to (2.37) everywhere.
Finally, the equation for $H_{1}$ reduces to

$$
\begin{equation*}
\left(A \partial_{i}^{2}+\frac{1}{A} \partial_{m}^{2}+\frac{1}{H_{2}^{2} H_{4} H_{4^{\prime}}} \partial_{a}^{2}\right) H_{1}=0, \tag{3.57}
\end{equation*}
$$

where $i=4,7, m=5,8, a=6,9$ here, and the function $A$ is defined by

$$
\begin{equation*}
A:=\frac{H_{4}}{H_{4^{\prime}}}=\frac{1-i c z}{1+i c z} . \tag{3.58}
\end{equation*}
$$

The differential equation (3.57) can be solved as follows. Introduce the change of variable

$$
\begin{equation*}
w:=\int H_{2}^{2} H_{4} H_{4^{\prime}} d z=\frac{z}{2(1+c z)}+\frac{1}{2 c} \ln (1+c z)-\frac{1}{4 c} \ln \left(1+c^{2} z^{2}\right), \tag{3.59}
\end{equation*}
$$

the equation (3.57) for $H_{1}$ becomes

$$
\begin{equation*}
\left(A \partial_{i}^{2}+\frac{1}{A} \partial_{m}^{2}+4 \partial_{w} \partial_{\bar{z}}\right) H_{1}=0 . \tag{3.60}
\end{equation*}
$$

This can be solved with the ansatz

$$
\begin{equation*}
H_{1}=1+\frac{R^{4}}{\rho^{4}}, \tag{3.61}
\end{equation*}
$$

where

$$
\begin{equation*}
\rho^{2}=B_{1}(w) x_{i}^{2}+B_{2}(w) x_{m}^{2}+C(w) \bar{z} . \tag{3.62}
\end{equation*}
$$

The equation (3.60) is satisfied if the following conditions on the coefficient functions $B_{1}(w), B_{2}(w)$ and $C(w)$ hold:

$$
\begin{align*}
C^{\prime}-3 C \frac{B_{1}^{\prime}}{B_{1}}+\frac{B_{2}}{A}-2 A B_{1} & =0  \tag{3.63}\\
C^{\prime}-3 C \frac{B_{2}^{\prime}}{B_{2}}+B_{1} A-2 \frac{B_{2}}{A} & =0  \tag{3.64}\\
C^{\prime} & =\frac{1}{2}\left(B_{1} A+\frac{B_{2}}{A}\right) \tag{3.65}
\end{align*}
$$

where ' here refers to differentiation with respect to $w$. It is easy to obtain from these equations

$$
\begin{align*}
\left(B_{1} B_{2}\right)^{\prime} & =0  \tag{3.66}\\
\left(\frac{C}{B_{1}}\right)^{\prime} & =A  \tag{3.67}\\
\left(\frac{C}{B_{2}}\right)^{\prime} & =\frac{1}{A} . \tag{3.68}
\end{align*}
$$

By rescaling $\rho$, we can set the integration constant of (3.66) to be 1 and we obtain

$$
\begin{equation*}
B_{1}=1 / B_{2} . \tag{3.69}
\end{equation*}
$$

The equations (3.67) and (3.68) then give

$$
\begin{equation*}
C B_{1}=\int \frac{1}{A} d w, \quad \frac{C}{B_{1}}=\int A d w \tag{3.70}
\end{equation*}
$$

and hence

$$
\begin{align*}
B_{1}(w(z)) & =\frac{1}{B_{2}(w(z))}=\sqrt{\frac{N(z)}{D(z)}}  \tag{3.71}\\
C(w(z)) & =\sqrt{N(z) D(z)} \tag{3.72}
\end{align*}
$$

where

$$
\begin{equation*}
N(z):=\int \frac{1}{A} d w, \quad D(z):=\int A d w \tag{3.73}
\end{equation*}
$$

Substituting the definition (3.58) for $A(z)$ and recalling (3.59), we have

$$
\begin{align*}
& N(z)=\frac{1}{4 c}\left[(1-i) \ln \frac{(1+c z)^{2}}{1+c^{2} z^{2}}+2(1+i) \tan ^{-1}(c z)-2(1+i) \frac{c^{2} z^{2}}{(1+c z)(i+c z)}\right]  \tag{3.74}\\
& D(z)=\frac{1}{4 c}\left[(1+i) \ln \frac{(1+c z)^{2}}{1+c^{2} z^{2}}+2(1-i) \tan ^{-1}(c z)-2(1-i) \frac{c^{2} z^{2}}{(1+c z)(-i+c z)}\right] \tag{3.75}
\end{align*}
$$

We also record the small $c$ expansions

$$
\begin{align*}
B_{1} & =1+i c z+O\left(c^{2} z^{2}\right)  \tag{3.76}\\
B_{2} & =1-i c z+O\left(c^{2} z^{2}\right)  \tag{3.77}\\
C & =z\left(1-c z+O\left(c^{2} z^{2}\right)\right) \tag{3.78}
\end{align*}
$$

where it is clear that the solution reduces back to the undeformed one $B_{1}=B_{2}=1, C=z$ when $c \rightarrow 0$.

The near horizon limit is given as before by taking

$$
\begin{equation*}
\tilde{x}^{a}:=x^{a} / \alpha^{\prime}, \quad \text { and } \quad U:=\rho / \alpha^{\prime} \tag{3.79}
\end{equation*}
$$

fixed in the $\alpha^{\prime} \rightarrow 0$ limit. We also scale $c$ such that

$$
\begin{equation*}
\tilde{c}:=\alpha^{\prime} c \tag{3.80}
\end{equation*}
$$

is fixed in the $\alpha^{\prime} \rightarrow 0$ limit. We obtain the near horizon metric

$$
\frac{d s^{2}}{\alpha^{\prime}}=\frac{U^{2}}{\sqrt{\lambda}} d x_{\mu}^{2}+\frac{\sqrt{\lambda}}{U^{2}}\left(\frac{1}{\tilde{A}}\left(d \tilde{x}_{4}^{2}+d \tilde{x}_{5}^{2}\right)+\tilde{A}\left(d \tilde{x}_{7}^{2}+d \tilde{x}_{8}^{2}\right)+\frac{1}{(1+\tilde{c} \tilde{z})^{2}\left(1+\tilde{c}^{2} \tilde{z}^{2}\right)} d \tilde{z} d \overline{\tilde{z}}\right)
$$

where we have defined

$$
\begin{equation*}
\tilde{z}:=z / \alpha^{\prime} \tag{3.81}
\end{equation*}
$$

The function $\tilde{A}$ is given by

$$
\begin{equation*}
\tilde{A}:=\frac{1-i \tilde{c} \tilde{z}}{1+i \tilde{c} \tilde{z}} \tag{3.82}
\end{equation*}
$$

and

$$
\begin{equation*}
U^{2}=B_{1} \tilde{x}_{i}^{2}+B_{2} \tilde{x}_{m}^{2}+\frac{C}{\alpha^{\prime}} \overline{\tilde{z}} \tag{3.83}
\end{equation*}
$$

where, with a slight abuse of notation, the coefficients $B_{1}, B_{2}$ and $C$ are obtained from (3.71)-(3.75) by replacing $c z$ with $\tilde{c} \tilde{z}$ everywhere. The RR 5 -form is given by $F_{0} / \alpha^{\prime 2}=d\left(U^{4}\right) d x^{0123} / \lambda+$ dual, together with the constant components (2.37). This supergravity solution is the dual for the non-anticommutative deformed $\mathcal{N}=4 \mathrm{SYM}$ with $\mathcal{N}=(1 / 2,0)$ supersymmetry.

## 4. Some consequences of the correspondence

In this section we will consider the effect of the non-anticommutative deformation on the field theory, as predicted by the supergravity dual. We will concentrate on the duality with $\mathcal{N}=(1,0)$ supersymmetry since in this case the supergravity background as constructed in section 3.1 is slightly simpler. In particular we will analyse the anomalous dimensions of the field theory operators.

As already noted in section 3.1 the metric is formally identical to the $A d S_{5} \times S^{5}$ metric of the undeformed theory, subject to the replacement of $z$ with $w=z /(1+c z)$. However, there is one subtlety which we must first address. Since we have deformed the field theory in a non-Hermitian way, the dual supergravity solution has been modified by a complex deformation. The resulting effect is the replacement of $z$ with $w$, but for $c \neq 0, w \neq z$. We therefore must be careful when interpreting this geometry. In particular, we need to identify the conformal boundary of the spacetime to relate bulk and boundary fields. Since we are viewing this theory as a deformation of the $\mathcal{N}=4$ theory, we will use the standard notion of the boundary as $r \rightarrow \infty$ where $r^{2}=x^{i} x_{i}+x^{m} x_{m}+|z|^{2}$. For $c \neq 0$ this differs from the complex quantity, $\rho^{2}=x^{i} x_{i}+x^{m} x_{m}+w \bar{z}$ which naturally appears in many quantities. However, generically $\rho$ diverges in the limit $r \rightarrow \infty$.

We will now consider the correspondence between bulk scalar fields and field theory operators. From the metric in equation (3.30) a scalar field $K$ with mass $m$ satisfies the Laplace equation which implies that

$$
\begin{equation*}
\left(\frac{\lambda}{\rho^{4}} \partial_{\mu}^{2}+\partial_{i}^{2}+\partial_{m}^{2}+4 \partial_{w} \partial_{\bar{z}}-m^{2} \frac{\sqrt{\lambda}}{\rho^{2}}\right) K=0 \tag{4.1}
\end{equation*}
$$

As for the undeformed case, solutions of this equation which are independent of the " 5 sphere" are given by

$$
\begin{equation*}
K=\frac{\xi^{\Delta}}{\left(x^{\mu} x_{\mu}+\xi^{2}\right)^{\Delta}} \tag{4.2}
\end{equation*}
$$

where $\xi=1 / \rho$ and $\Delta=2+\sqrt{4+m^{2}}$. We will now see that, despite the distinction between $\rho$ and $r$, these states are dual to field theory operators with scaling dimension $\Delta$. Therefore there is a class of field theory operators whose spectrum is not deformed. Note however that there are two possible ways in which the spectrum of operators can be deformed. There are the other solutions to the ten-dimensional Laplace equation which have a dependence on the " 5 -sphere". Since this is deformed, the resulting spectrum of 5 -dimensional masses
will be changed. Also, the ten-dimensional spectrum of the full string theory is likely to depend on the deformation, giving a dependence of $m^{2}$ on $c$ for string theory states.

We will now use the above solution $K\left(\xi, x^{\mu}\right)$ to give the 5 -dimensional bulk to boundary propagator for these scalars and calculate the two-point function of the dual field theory operators using standard techniques. So, a boundary field $\phi_{0}\left(x^{\mu}\right)$ is a source for the bulk field configuration

$$
\begin{equation*}
\phi\left(\xi, x^{\mu}\right)=\int \mathrm{d}^{4} x^{\prime} \frac{\xi^{\Delta}}{\left(\left|x-x^{\prime}\right|^{2}+\xi^{2}\right)^{\Delta}} \phi_{0}\left(x^{\prime}\right) \tag{4.3}
\end{equation*}
$$

To calculate the two-point function we need to consider the dependence of the action for the bulk scalar field on its "boundary values" $\phi_{0}(x)$. This is

$$
\begin{align*}
I & =\int \mathrm{d}^{4} x \mathrm{~d} r \mathrm{~d}^{5} \Omega \frac{1}{2} \sqrt{g}\left(\partial_{M} \phi \partial_{N} \phi g^{M N}+m^{2} \phi^{2}\right)  \tag{4.4}\\
& =\frac{1}{2} \int \mathrm{~d}^{4} x \mathrm{~d}^{5} \Omega\left(\sqrt{g} \phi g^{r N} \partial_{N} \phi\right)_{r \rightarrow \infty} \tag{4.5}
\end{align*}
$$

where we have used integration by parts and the equation of motion for $\phi$ to perform the integral over $r$.

We can now use the above relation between $\phi$ and $\phi_{0}$, together with the following standard polar parametrisation of the coordinates

$$
\begin{align*}
x^{6}+i x^{9} & =r \cos \alpha \mathrm{e}^{i \phi_{1}}  \tag{4.6}\\
x^{4}+i x^{5} & =r \sin \alpha \cos \theta \mathrm{e}^{i \phi_{2}}  \tag{4.7}\\
x^{7}+i x^{8} & =r \sin \alpha \sin \theta \mathrm{e}^{i \phi_{3}} \tag{4.8}
\end{align*}
$$

to write the action explicitly in terms of the boundary sources $\phi_{0}$. Note that for fixed angles, $\xi \rightarrow 0$ as $r \rightarrow \infty$. Explicitly, we find

$$
\begin{align*}
\sqrt{g}= & r^{5} \xi^{2} H_{2} \sin ^{3} \alpha \cos \alpha \sin \theta \cos \theta  \tag{4.9}\\
\phi(\xi \rightarrow 0, x)= & \xi^{4-\Delta} \phi_{0}(x)  \tag{4.10}\\
g^{r N} \partial_{N} \phi= & -\frac{\Delta}{H_{2}^{2}}\left(\left(1+\left(H_{2}^{2}-1\right) \sin ^{2} \alpha\right) \partial_{r} \rho+\frac{1}{r}\left(H_{2}^{2}-1\right) \sin \alpha \cos \alpha \partial_{\alpha} \rho\right) \times \\
& \times \int \mathrm{d}^{4} x^{\prime} \frac{\phi_{0}\left(x^{\prime}\right)}{\left|x-x^{\prime}\right|^{2 \Delta}} \tag{4.11}
\end{align*}
$$

where in the last result we have kept only the leading order terms as $\xi \rightarrow 0$. Putting everything together we find the expression for the two-point function of the operator dual to the scalar field

$$
\begin{align*}
\left\langle\mathcal{O}(x) \mathcal{O}\left(x^{\prime}\right)\right\rangle= & \frac{\delta I}{\delta \phi_{0}(x) \delta \phi_{0}\left(x^{\prime}\right)} \\
= & -\frac{\Delta}{2} \frac{1}{\left|x-x^{\prime}\right|^{2 \Delta}} \int \mathrm{~d}^{5} \Omega \sin ^{3} \alpha \cos \alpha \sin \theta \cos \theta \frac{r^{5}}{\rho^{5} H_{2}} \times \\
& \times\left(\left(1+\left(H_{2}^{2}-1\right) \sin ^{2} \alpha\right) \partial_{r} \rho+\frac{1}{r}\left(H_{2}^{2}-1\right) \sin \alpha \cos \alpha \partial_{\alpha} \rho\right)  \tag{4.12}\\
= & \frac{C}{\left|x-x^{\prime}\right|^{2 \Delta}} \tag{4.13}
\end{align*}
$$

where the constant $C$ is given by the integral in the previous line which is to be evaluated in the limit $r \rightarrow \infty$. Actually evaluating the integral is not straightforward since the large $r$ behaviour is different for $\alpha=0$ and $\alpha \neq 0$, as can easily be seen by considering the explicit expression for $\rho^{2}=r^{2} \sin ^{2} \alpha+r^{2} \cos ^{2} \alpha /\left(1+c r \cos \alpha \mathrm{e}^{i \phi_{1}}\right)$. Nevertheless the final result clearly indicates that the anomalous dimension of the operator $\mathcal{O}$ is given by $\Delta$. Hence, for this class of operator, the only corrections to this dimension, as compared to the undeformed theory, can come from the possible dependence of the bulk mass $m$ on the deformation parameter $c$.

Similar results will follow for field theory operators dual to other bulk fields. Due to the nature of the deformation, we expect that the spectrum of BPS states is simply a subset of the BPS states in the undeformed geometry. This would then correspond to the prediction that the scaling dimensions of the chiral operators in the field theory are the same as in the $\mathcal{N}=4$ theory, but that the rest of the theory will be deformed.

## 5. Discussions

In this paper we have constructed the supergravity duals for the non-anticommutative deformed $\mathcal{N}=4$ supersymmetric Yang-Mills theory with $\mathcal{N}=(1,0)$ and $\mathcal{N}=(1 / 2,0)$ supersymmetries. The supergravity solution consists of a metric which is a complex deformation of the $A d S_{5} \times S^{5}$ metric, and a RR 5-form fields with complex constant components. The fact that the metric is non-dilatonic suggests that the field theory coupling is not renormalized. It will be interesting to check this explicitly.

Deformed by non-anticommutativity of the fermionic components of the superspace, the non-anticommutative field theory breaks supersymmetry in a novel non-traditional way. Nevertheless it preserves many remarkable properties of the usual supersymmetric field theories. It will be interesting to analyse and understand more this kind of supersymmetric breaking from the supergravity point of view.

The supergravity background dual to the non-anticommutative gauge theory is complex. The imaginary nature of the RR 5-form is easy to understand and is a direct consequence of solving the self-duality condition in Euclidean space. The imaginary nature of the metric is more obscure. Although we have demonstrated that one can nevertheless extract physical information such as the dimensions of operators in a more or less the standard way using the bulk-to-boundary approach, it will be good to have a deeper understanding on the imaginary nature of the metric. We recall that the complexity of the metric (and the flux background) is a direct reflection of the fact that the non-anticommutative field theory is non-Hermitian. With an analysis which is based on a reduction to the quantum mechanics, it has been suggested [40] that non-anticommutative theory is unitary in a more general sense [41]. This suggests something similar in the dual supergravity description. As a first step, it is natural to try to find the corresponding phenomena in the supergravity side when a similar reduction of degree of freedoms is performed. In the mini-superspace approximation, one can work out the canonical Hamiltonian. Due to the presence of complex components in the metric, the Hamiltonian is not real. We conjecture that the Hamiltonian is pseudo-real in a sense similar to its field theory counterpart. This
would provide a physical understanding of the nature of the complexity of the supergravity background. We leave this interesting question for future analysis.

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## A. Notation and convention

We denote by $\mu=0,1,2,3$ the directions in the 4 -dimensional Euclidean worldvolume of the $D 3$-branes, $a=4,5,6,7,8,9$ the transverse directions, and $\alpha, \dot{\alpha}=1,2$ the spinor indices. We follow the notation of (34]. In particular, spinor indices are raised and lowered by the $\varepsilon$-tensor with the convention $\varepsilon^{12}=-\varepsilon_{12}=1$.

Decomposing $\mathrm{SO}(10)$ into $\mathrm{SO}(4) \times \mathrm{SO}(6)$, the ten-dimensional gamma matrices are given by

$$
\begin{equation*}
\Gamma_{(10)}^{\mu}=\gamma^{\mu} \otimes 1, \quad \Gamma_{(10)}^{a}=\gamma^{5} \otimes \Gamma^{a}, \tag{A.1}
\end{equation*}
$$

where

$$
\gamma^{\mu}=\left(\begin{array}{cc}
0 & \sigma^{\mu}  \tag{A.2}\\
\bar{\sigma}^{\mu} & 0
\end{array}\right), \quad \Gamma^{a}=\left(\begin{array}{cc}
0 & \Sigma^{a} \\
\bar{\Sigma}^{a} & 0
\end{array}\right) .
$$

Here the matrices $\left(\sigma^{\mu}\right)_{\alpha \dot{\beta}}$ and $\left(\bar{\sigma}^{\mu}\right)^{\dot{\alpha} \beta}$ are given by

$$
\begin{align*}
& \sigma_{\mu}=\left(i \tau^{1}, i \tau^{2}, i \tau^{3}, 1\right) \\
& \bar{\sigma}_{\mu}=\left(-i \tau^{1},-i \tau^{2},-i \tau^{3}, 1\right), \tag{A.3}
\end{align*}
$$

where $\tau^{i}(i=1,2,3)$ are the Pauli matrices. They satisfy the Clifford algebra

$$
\begin{equation*}
\sigma_{\mu} \bar{\sigma}_{\nu}+\sigma_{\nu} \bar{\sigma}_{\mu}=2 \delta_{\mu \nu} \mathbf{1} \tag{A.4}
\end{equation*}
$$

The Lorentz generators are defined by

$$
\begin{equation*}
\sigma^{\mu \nu}=\frac{1}{4}\left(\sigma^{\mu} \bar{\sigma}^{\nu}-\sigma^{\nu} \bar{\sigma}^{\mu}\right), \quad \bar{\sigma}_{\mu \nu}=\frac{1}{4}\left(\bar{\sigma}_{\mu} \sigma_{\nu}-\bar{\sigma}_{\nu} \sigma_{\mu}\right) . \tag{A.5}
\end{equation*}
$$

The matrices $\left(\sigma_{\mu \nu}\right)_{\alpha \beta},\left(\tilde{\sigma}_{\mu \nu}\right)^{\dot{\alpha} \dot{\beta}}$ are symmetric in the spinor indices. Moreover $\sigma_{\mu \nu}$ is selfdual and $\tilde{\sigma}_{\mu \nu}$ is anti self-dual with respect to the $\mu, \nu$ indices.

The gamma matrices for six-dimensional part are given by

$$
\begin{align*}
& \Sigma^{a}=\left(\eta^{3},-i \bar{\eta}^{3}, \eta^{2},-i \bar{\eta}^{2}, \eta^{1}, i \bar{\eta}^{1}\right), \\
& \bar{\Sigma}^{a}=\left(-\eta^{3},-i \bar{\eta}^{3},-\eta^{2},-i \bar{\eta}^{2},-\eta^{1}, i \bar{\eta}^{1}\right), \tag{A.6}
\end{align*}
$$

where $a=4, \ldots, 9 . \eta_{\mu \nu}^{a}$ and $\bar{\eta}_{\mu \nu}^{a}$ are the 't Hooft symbols, which are defined by

$$
\begin{equation*}
\sigma_{\mu \nu}=\frac{i}{2} \eta_{\mu \nu}^{a} \tau^{a}, \quad \bar{\sigma}_{\mu \nu}=\frac{i}{2} \bar{\eta}_{\mu \nu}^{a} \tau^{a} . \tag{A.7}
\end{equation*}
$$

The matrices (A.6) satisfy the Clifford algebra

$$
\begin{equation*}
\left(\Sigma^{a}\right)^{A B}\left(\bar{\Sigma}^{b}\right)_{B C}+\left(\Sigma^{b}\right)^{A B}\left(\bar{\Sigma}^{a}\right)_{B C}=2 \delta^{a b} \delta_{C}^{A} . \tag{A.8}
\end{equation*}
$$

The charge conjugation matrix is block diagonal in this basis

$$
\begin{equation*}
\mathcal{C}=\mathcal{C}_{(4)} \otimes \mathcal{C}_{(6)}, \tag{A.9}
\end{equation*}
$$

where

$$
\mathcal{C}_{(4)}=\left(\begin{array}{cc}
-\epsilon^{\alpha \beta} & 0  \tag{A.10}\\
0 & -\epsilon_{\dot{\alpha} \dot{\beta}}
\end{array}\right), \quad \mathcal{C}_{(6)}=\left(\begin{array}{cc}
0 & -i \delta_{A}{ }^{B} \\
-i \delta_{B}^{A} & 0
\end{array}\right) .
$$

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[^0]:    ${ }^{1}$ Non-anticommutative $\mathcal{N}=4$ super Yang-Mills theory can also be realized through deforming the constraint equations defined on the Euclidean superspace $\mathbb{R}^{4 \mid 16}$ 14].
    ${ }^{2}$ In Euclidean space, the Grassmannian-odd coordinates $\theta^{\alpha}$ and $\bar{\theta}^{\dot{\alpha}}$ are not related by complex conjugation, therefore it is more convenient to denote the simple $\mathcal{N}=1$ supersymmetry as $\mathcal{N}=(1 / 2,1 / 2)$. For the more general extended case, one can have $\mathcal{N}=(n / 2, m / 2)$ supersymmetry where $n, m$ are the number of left and right chiral spinorial supersymmetry generators.

[^1]:    ${ }^{3} \mathcal{F}$ and $F_{\mu_{1} \cdots \mu_{p+1}}$ are of dimension $[L]^{-2}$ here. This is different from the normal dimension of $[L]^{-1}$ for the RR gauge field strength in supergravity theory

